Show *all* of your work and *explain* your answers fully. There is a total of 90 possible points. If you use a calculator or software package on a problem be sure to write down both the input and output.

1. Prove that the set  $C = \{2 + x + 3x^2, 1 - 2x - x^2, -3 + x + 2x^2\}$  is a basis of  $P_2$ , the vector space of polynomials with degree at most 2. (20 points)

Solution: With an application of Theorem G, we can save a bit of work. Lets first establish that C is a linearly independent set, by starting with a relation of linear dependence (Definition RLD),

$$\mathbf{0} = 0 + 0x + 0x^{2}$$
  
=  $a_{1} (2 + x + 3x^{2}) + a_{2} (1 - 2x - x^{2}) + a_{3} (-3 + x + 2x^{2})$   
=  $(2a_{1} + a_{2} - 3a_{3}) + (a_{1} - 2a_{2} + a_{3}) x + (3a_{1} - a_{2} + 2a_{3}) x^{2}$ 

The definition of equality in  $P_2$  allows us to equate coefficients, which leads to a homogeneous system of three equations in the unknowns  $a_1$ ,  $a_2$ ,  $a_3$ , with coefficient matrix

$$A = \begin{bmatrix} 2 & 1 & -3 \\ 1 & -2 & 1 \\ 3 & -1 & 2 \end{bmatrix}$$

Check that A row-reduces to the identity matrix  $I_3$  and so by Theorem NMRRI is a nonsingular matrix. Then by Definition NM, the only solution to the homogeneous system is  $a_1 = a_2 = a_3 = 0$ . By Definition LI, C is linearly independent.

We know by Theorem DP that  $P_2$  has dimension 3. Because C is a set of size 3, Theorem G tells us that C is a basis of  $P_2$ , sparing us the necessity of checking that C spans  $P_2$ .

2. Prove that D is a spanning set for the subspace X of  $M_{22}$ . (20 points)

$$D = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 6 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & -2 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 3 \end{bmatrix} \right\} \qquad X = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \middle| 6a - 2b + 3c - d = 0 \right\} \subseteq M_{22}$$

Solution: According to Definition TSVS we need to establish the set equality  $\langle D \rangle = X$  (Definition SE). Check that each of three elements of D is an element of X (each passes the membership criteria), so by Definition SS, we have the first set inclusion,  $\langle D \rangle \subseteq X$ .

To establish the second set inclusion,  $X \subseteq \langle D \rangle$ , we grab a generic element of X and ask if it can be written as a linear combination of the three elements of D? With the assumption that 6a - 2b + 3c - d = 0 are there scalars  $\alpha_1$ ,  $\alpha_2$ ,  $\alpha_3$  such that

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \alpha_1 \begin{bmatrix} 1 & 0 \\ 0 & 6 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 & 1 \\ 0 & -2 \end{bmatrix} + \alpha_3 \begin{bmatrix} 0 & 0 \\ 1 & 3 \end{bmatrix}$$

We massage the right-hand side,

$$= \begin{bmatrix} \alpha_1 & \alpha_2 \\ \alpha_3 & 6\alpha_1 - 2\alpha_2 + 3\alpha_3 \end{bmatrix}$$

If we apply the definition of matrix equality (Definition ME) we get a system of four equations in the three variables  $\alpha_1$ ,  $\alpha_2$ ,  $\alpha_3$  which is represented by the augmented matrix,

[1	0	0	a	
0	1	0	b	
0	0	1	c	
6	-2	3	d	

This matrix is very nearly in reduced row-echelon form, we just need to perform (by hand) the operations  $-6R_1 + R_4$ ,  $2R_2 + R_4$ ,  $-3R_3 + R_4$  and apply the knowledge that 6a - 2b + 3c - d = 0,

$$\begin{bmatrix} 1 & 0 & 0 & a \\ 0 & 1 & 0 & b \\ 0 & 0 & 1 & c \\ 6 & -2 & 3 & d \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & a \\ 0 & 1 & 0 & b \\ 0 & 0 & 1 & c \\ 0 & 0 & 0 & -6a + 2b - 3c + d \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & a \\ 0 & 1 & 0 & b \\ 0 & 0 & 1 & c \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

By Theorem RCLS we see that the system is consistent, so there are scalars  $\alpha_1$ ,  $\alpha_2$ ,  $\alpha_3$ , and so  $X \subseteq \langle D \rangle$ . By Definition SE, we have  $X = \langle D \rangle$  and so D spans X.

Another approach to this problem is to begin with the set X and vary its description until a generic element is "obviously" written as a linear combination of the three elements in D. Note too that Theorem G does not apply since we have no advance knowledge of the dimension of X. (If we establish the linear independence of D then we could see that  $\dim(X) = 3$ .)

3. The set  $Y = \{a + bx + cx^2 + dx^3 \mid a + b + 3c - 5d = 0, 2a - b + 3c + 4d = 0\}$  is a subspace of  $P_3$ , the vector space of polynomials with degree at most 3 (you may assume this much). With complete justification, determine the dimension of Y. (20 points)

Solution: We have to construct a basis of Y before we can (easily) compute the dimension. By manipulating the description of Y we can construct a spanning set, and then check the set for linear independence. First, consider the homogeneous system whose coefficient matrix we now row-reduce,

$$\begin{bmatrix} 1 & 1 & 3 & -5 \\ 2 & -1 & 3 & -4 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 2 & -3 \\ 0 & 1 & 1 & -2 \end{bmatrix}$$

We can begin modifying Y by replacing the membership criteria with an equivalent homogeneous system, based on these two row-equivalent coefficient matrices,

$$Y = \left\{ a + bx + cx^{2} + dx^{3} \mid a + b + 3c - 5d = 0, 2a - b + 3c + 4d = 0 \right\}$$
  
=  $\left\{ a + bx + cx^{2} + dx^{3} \mid a + 2c - 3d = 0, b + c - 2d = 0 \right\}$   
=  $\left\{ a + bx + cx^{2} + dx^{3} \mid a = -2c + 3d, b = -c + 2d \right\}$   
=  $\left\{ (-2c + 3d) + (-c + 2d)x + cx^{2} + dx^{3} \mid c, d \in \mathbb{C} \right\}$   
=  $\left\{ (-2c - cx + cx^{2}) + (3d + 2dx + dx^{3}) \mid c, d \in \mathbb{C} \right\}$   
=  $\left\{ c (-2 - x + x^{2}) + d (3 + 2x + x^{3}) \mid c, d \in \mathbb{C} \right\}$   
=  $\left\{ \left\{ (-2c - x + x^{2}, 3 + 2x + x^{3}) \mid c, d \in \mathbb{C} \right\}$ 

So  $B = \{-2 - x + x^2, 3 + 2x + x^3\}$  is a spanning set for Y. Is B linearly independent? Let  $\alpha_1$  and  $\alpha_2$  be the unknown scalars in a relation of linear dependence,

$$\mathbf{0} = 0 + 0x + 0x^{2} + 0x^{4}$$
  
=  $\alpha_{1} \left( -2 - x + x^{2} \right) + \alpha_{2} \left( 3 + 2x + x^{3} \right)$   
=  $\left( -2\alpha_{1} + 3\alpha_{2} \right) + \left( -\alpha_{1} + 2\alpha_{2} \right) + \alpha_{1}x^{2} + \alpha_{2}x^{3}$ 

The equality of the coefficients  $x^2$  and  $x^3$  implies that  $\alpha_1 = \alpha_2 = 0$ . So by Definition LI, the set *B* is linearly independent. By Definition B, we know *B* is a basis of *Y* with size 2, and so dim (Y) = 2.

4. Illustrate the use of the three tests of Theorem TSS to prove that W is a subspace of  $\mathbb{C}^3$ . (15 points)

$$W = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \middle| 2x_1 + 5x_2 - 7x_3 = 0 \right\}$$

Solution: See your Section S class notes, Example SC3 and the solution to Exercise S.M20. In particular, the **existence** of the zero vector is not in question, but its **membership** in W could be checked as part of testing that W is non-empty. Also, be certain that your checks of the two types of closure are clearly written as establishing implications (clearly stated hypotheses, and their application in establishing the right conclusion).

5. Suppose that  $B = {\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \dots, \mathbf{x}_n}$  is a basis for  $\mathbb{C}^n$ . Let A be a nonsingular matrix of size n and define  $C = {A\mathbf{x}_1, A\mathbf{x}_2, \dots, A\mathbf{x}_n}$ .

Choose one of the following two statements (by circling it) and provide a proof. You **must** indicate which statement you have chosen to prove, or there will be no credit. (15 points)

- (a) C is a linearly independent set.
- (b) C is a spanning set of  $\mathbb{C}^n$ .

Solution: We provide proofs of both statements. As a practical matter, knowing that the dimension of  $\mathbb{C}^n$  is n (Theorem DCM), we can apply Theorem G to prove one statement after we first prove the other. However this requires that we are certain that the set C has n distinct elements, which requires a short proof that turns on A being nonsingular.

(a) C is linearly independent. Work on a relation of linear dependence on C,

$0 = a_1 A \mathbf{x}_1 + a_2 A \mathbf{x}_2 + a_3 A \mathbf{x}_3 + \dots + a_n A \mathbf{x}_n$	Definition RLD
$= Aa_1\mathbf{x}_1 + Aa_2\mathbf{x}_2 + Aa_3\mathbf{x}_3 + \dots + Aa_n\mathbf{x}_n$	Theorem MMSMM
$= A \left( a_1 \mathbf{x}_1 + a_2 \mathbf{x}_2 + a_3 \mathbf{x}_3 + \dots + a_n \mathbf{x}_n \right)$	Theorem MMDAA

Since A is nonsingular, Definition NM and Theorem SLEMM allows us to conclude that

$$a_1\mathbf{x}_1 + a_2\mathbf{x}_2 + \dots + a_n\mathbf{x}_n = \mathbf{0}$$

But this is a relation of linear dependence of the linearly independent set B, so the scalars are trivial,  $a_1 = a_2 = a_3 = \cdots = a_n = 0$ . By Definition LI, the set C is linearly independent.

(b) C spans  $\mathbb{C}^n$ . Given an arbitrary vector  $\mathbf{y} \in \mathbb{C}^n$ , can it be expressed as a linear combination of the vectors in C? Since A is a nonsingular matrix we can define the vector  $\mathbf{w}$  to be the unique solution of the system  $\mathcal{LS}(A, \mathbf{y})$  (Theorem NMUS). Since  $\mathbf{w} \in \mathbb{C}^n$  we can write  $\mathbf{w}$  as a linear combination of the vectors in the basis B. So there are scalars,  $b_1, b_2, b_3, \ldots, b_n$  such that

$$\mathbf{w} = b_1 \mathbf{x}_1 + b_2 \mathbf{x}_2 + b_3 \mathbf{x}_3 + \dots + b_n \mathbf{x}_n$$

Then,

$\mathbf{y} = A\mathbf{w}$	Theorem SLEMM
$=A\left(b_1\mathbf{x}_1+b_2\mathbf{x}_2+b_3\mathbf{x}_3+\cdots+b_n\mathbf{x}_n\right)$	Definition TSVS
$= Ab_1\mathbf{x}_1 + Ab_2\mathbf{x}_2 + Ab_3\mathbf{x}_3 + \dots + Ab_n\mathbf{x}_n$	Theorem MMDAA
$= b_1 A \mathbf{x}_1 + b_2 A \mathbf{x}_2 + b_3 A \mathbf{x}_3 + \dots + b_n A \mathbf{x}_n$	Theorem MMSMM

So we can write an arbitrary vector of  $\mathbb{C}^n$  as a linear combination of the elements of C. In other words, C spans  $\mathbb{C}^n$  (Definition TSVS).